

# *Wave Breaking Dissipation and Wave/Current Interactions*

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27 November 2007

# Uncertainty Quantification Group

- Faculty
  - JMR (Math, Physics, Atmospheric Science)
  - Shankar Venkataramani (Math)
  - Kevin Lin (Math)
  - Rabi Bhattacharya (Math, Statistics)
  - Kobus Barnard (Computer Science)
  - Hermann Flaschka (Math)
- Post-Docs
  - P. Krause
  - J. Ramírez
  - P. Dostert
  - T.-T. Shieh
- Graduate Students: 15, Undergraduate Students: 2.



# Focus Problems

## Weather



## Hydrogeology



## Vision/Structure



**Estimation**, Sampling, Dynamical Systems, Machine-Learning, Computer Grammars, Large-scale Computing, Statistical Analysis, Data Management.

*UQG*

# Wave Breaking Dissipation Team

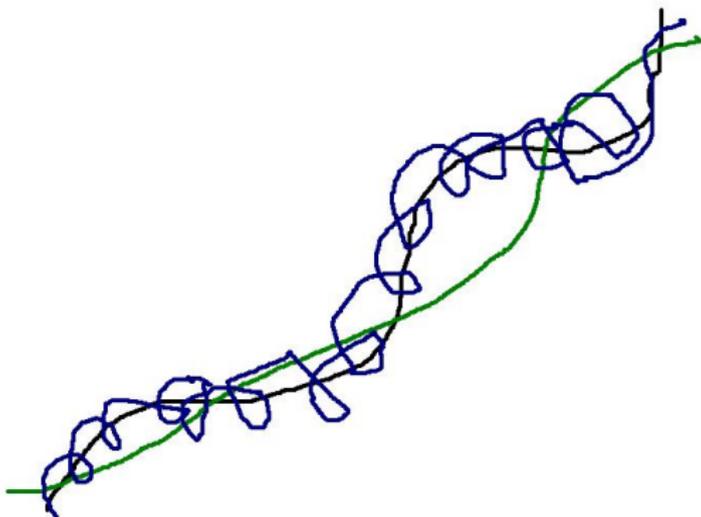
## COLLABORATORS

Jorge Ramírez & Brad Weir	University of Arizona
Emily Lane	NIWA, New Zealand
Jim McWilliams	UCLA
Michael Banner	UNSW, Australia

# Lagrangian/Eulerian Projections in Multiscale Setting

## THEME

Multiscale projection of systems of (mostly) hyperbolic equations between the Eulerian and Lagrangian frames.



## Outcomes Relevant to Ocean Dynamics:

- Wave/current interaction theory (Vortex Force)
- Stress and pressure-gradient adjustments due to the radiation stress
- Interactions of waves and currents in littoral current instabilities
- Interaction of waves and currents in rip current instabilities
- The rip surge, a different type of rip current
- Origin and maintenance of shore-face connected sand ridges
- Oceanic Lagrangian data assimilation
- *Inclusion of Dissipative Mechanisms via stochastic parametrization (wave breaking, bottom drag)*

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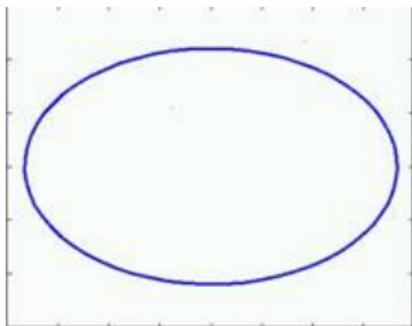
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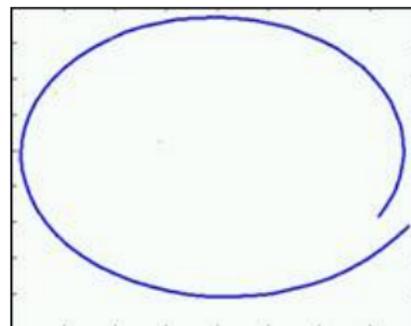
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# Transport Due to Oscillatory Flow

$$\begin{aligned}\frac{d\mathbf{X}}{dt} &= \mathbf{V} \\ \mathbf{X}(0) &= \mathbf{X}_0\end{aligned}$$



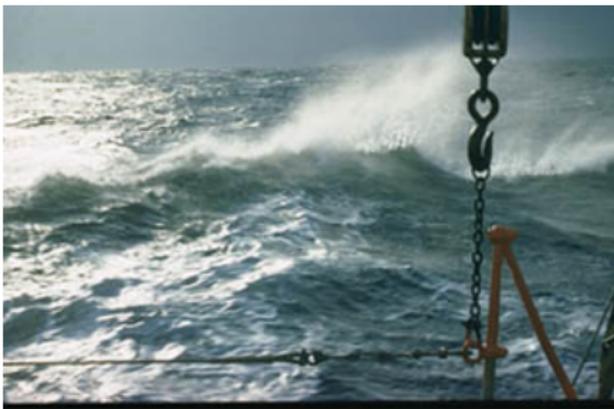
**Figure:** Particle Motion Under Linear Waves



**Figure:** Particle Motion Under Nonlinear Waves



# Lagrangian Motion Under White Capping



$$d\mathbf{X} = \mathbf{V}dt$$

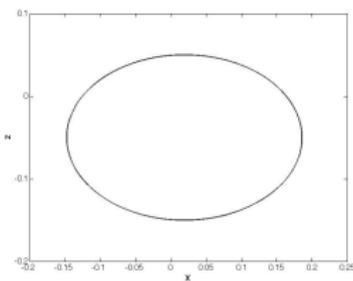
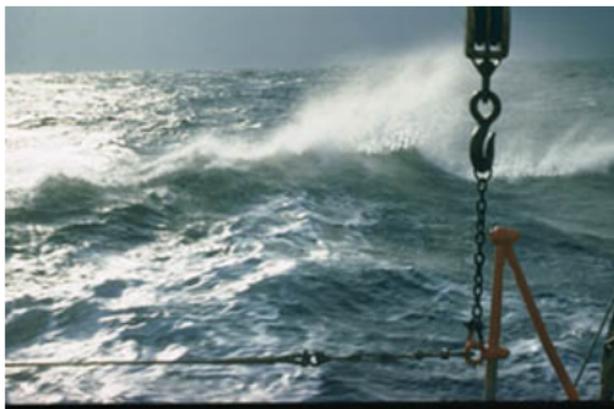


Figure: Deterministic

# Lagrangian Motion Under White Capping



$$d\mathbf{X} = \mathbf{V}dt$$

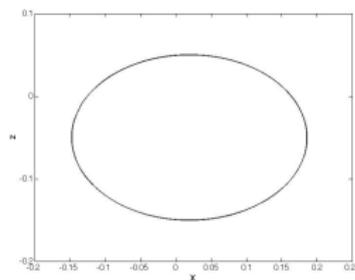


Figure: Deterministic

# Lagrangian Motion Under White Capping



$$d\mathbf{X}_t = \mathbf{V}(\mathbf{X}, t)dt + d\mathbf{W}_t(\mathbf{X}, t)$$

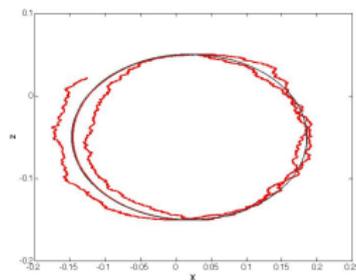
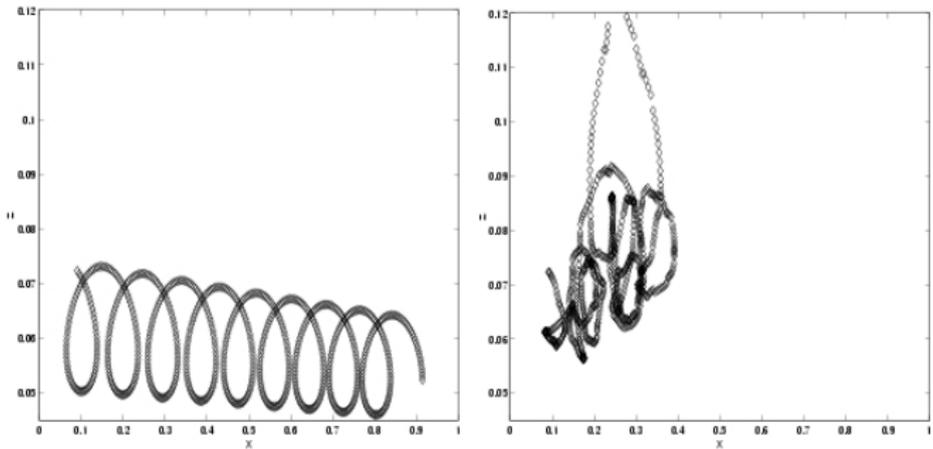


Figure: Stochastic



J. Restrepo and G. Leaf *Wave-generated Transport Induced by Ideal Waves* J. Phys. Oceanogr. 2002

# What Stochastic Model?

$$d\mathbf{X}_t = \mathbf{V}(\mathbf{X}, t)dt + d\mathbf{W}_t(\mathbf{X}, t)$$

Experiments are needed to determine the right model

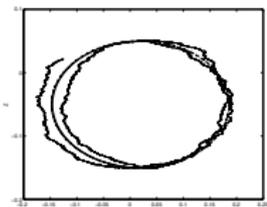


Figure:  $d\mathbf{W}$  standard white noise

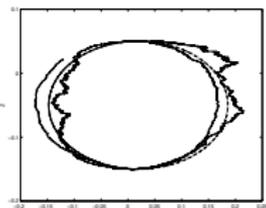


Figure:  $d\mathbf{W}$  with added mean-reverting process

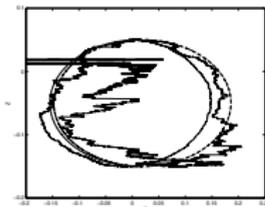


Figure:  $d\mathbf{W}$  with added jump process

# Why a Stochastic Model?

- **Ideal way to parameterize some aspects of small scale motions**
- Parameterization permits stronger connection to field data

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- Ideal way to parameterize some aspects of small scale motions
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## Main Goals

- How does dissipation at wave scales manifest itself at longer time scales?
- Can we find the right stochastic parameterization?
- Can we parameterize dissipation in such a way that we use global information more efficiently? (Lagrangian/Eulerian)

# Scale Range of the Model

- 10 secs-months
- 100m-basin scale
- Speed: waves  $>$  currents
- $kH \sim 1$
- Applications:
  - climate dynamics  
(transport)
  - erodible bed dynamics
  - river plume evolution
  - algal/plankton blooms
  - pollution



J. McWilliams and J. M. Restrepo *The Wave-driven Ocean Circulation* J. Phys. Oceanogr. (1999)

J. Restrepo *Wave-Current Interactions and Shore-connected Bars* J. Estuarine Sci. (2001)

J. McWilliams, J. M. Restrepo, E. Lane *An asymptotic Theory for the Interaction of Waves and Currents in Coastal Waters* J. Fluid Mechanics (2004)

E. Lane, J. M. Restrepo, J. McWilliams *Wave-Current Interaction: A comparison of radiation-stress and vortex-force representations* J. Phys Oceanogr (2007)

# Conservative Wave/Current Model

## GOALS:

- Formulate a model on the larger spatio-temporal scales that accurately captures the dynamics of the small scales *without* requiring solving for these on the smaller scales.
- Describe *how* waves affect currents and vice versa.
- The model should be extensible, to eventually include:
  - tracer dynamics.
  - wave generation.
  - dissipation in the bulk, due to breaking events, due to bottom drag.
  - wind forcing.

# Conservative Wave/Current Model

## STRATEGY

- Use a quasi geostrophic flow model or a shallow water wave model
- Introduce three scales: waves  $\mathbf{u}^w$ , long-waves  $\mathbf{u}^{lw}$ , currents  $\mathbf{v}$ .
- Use asymptotics balances with waves of comparable or larger amplitude than currents
- Use time-averaging and projections to derive filtered equations

# Multi-scale Methodology

Momentum, Continuity, and Tracer Equations:

$$\begin{aligned} \mathbf{q}_t + (\mathbf{q} \cdot \nabla) \mathbf{q} + 2\Omega \times \mathbf{q} - \tilde{b} \hat{\mathbf{z}} + \frac{1}{\rho_0} \nabla \tilde{p} &= \mathbf{v} \nabla^2 \mathbf{q}, \\ \nabla \cdot \mathbf{q} &= 0, \end{aligned}$$

$$\frac{D\tilde{\theta}}{Dt} = \kappa \nabla^2 \tilde{\theta},$$

The surface boundary conditions at  $z = \eta(\mathbf{x}_h, t)$  are the following:

$$\begin{aligned} w &= \frac{D\eta}{Dt}, & \tilde{p} &= g\rho_0\eta + \tilde{p}_a, \\ \mathbf{v} \frac{\partial \mathbf{q}}{\partial z} &= \frac{1}{\rho_0} \boldsymbol{\tau}, & \kappa \frac{\partial \tilde{\theta}}{\partial z} &= \mathcal{I}. \end{aligned}$$

## Linear Gravity Waves:

$$\begin{aligned}\mathbf{u}_k^w &= -\nabla\phi_k^w, \\ \phi_k^w &= -\frac{e^{kz}}{k} \frac{\partial\eta_k^w(\mathbf{x}_h, t)}{\partial t}, \\ \eta_k^w &= a_k \cos[\mathbf{k}_h \cdot \mathbf{x}_h - \sigma_k t],\end{aligned}$$

$$\mathbf{q} = \varepsilon[\mathbf{u}^w(\mathbf{x}, t) + \varepsilon\mathbf{v}(\mathbf{x}, t_s, t)],$$

where  $\boldsymbol{\omega} = \nabla \times \mathbf{q} = \nabla \times \mathbf{v}$

$$\begin{aligned} \frac{\partial \boldsymbol{\omega}}{\partial t} + \varepsilon^2 \frac{\partial \boldsymbol{\omega}}{\partial t_s} &= \nabla \times [\varepsilon(\mathbf{u}^w + \varepsilon\mathbf{v}) \times 2\boldsymbol{\Omega}] + \nabla \times [\varepsilon(\mathbf{u}^w + \varepsilon\mathbf{v}) \times \boldsymbol{\omega}] \\ &\quad \varepsilon^2 \mathbf{v} \nabla^2 \boldsymbol{\omega} + \varepsilon^2 \nabla \times \hat{\mathbf{z}} b, \end{aligned}$$

Lowest orders in vorticity:

$$\boldsymbol{\omega}_0 = \boldsymbol{\omega}_0(\mathbf{x}, t_s).$$

$$\boldsymbol{\omega}_1 = \nabla \times (\mathbf{U} \times \mathbf{Z}),$$

where  $\mathbf{U} \equiv \int^t \mathbf{u}^w(\cdot, s) ds$  and  $\mathbf{Z} = \boldsymbol{\omega} + 2\boldsymbol{\Omega}$ .

The next order up yields the wave/current equation, after time averaging over waves:

$$\frac{\partial \mathbf{v}_0}{\partial t_s} - \mathbf{V} \times \mathbf{Z} + \nabla \Phi - b_0 \hat{\mathbf{z}} = \nu \nabla^2 \mathbf{v}_0,$$

where we define

$$\Phi = p_0 + \frac{1}{2} \mathbf{V}^2.$$

$$\mathbf{V} = \mathbf{v} + \mathbf{u}^{St}, \quad \mathbf{Z} = \boldsymbol{\omega} + 2\boldsymbol{\Omega}$$

where  $\mathbf{v} = \mathbf{v}_0 + \mathbf{v}'$ , where  $\langle \mathbf{v} \rangle = \mathbf{v}_0$ . The **Stokes Drift Velocity** is

$$\mathbf{u}^{St} = \left\langle \int^t \mathbf{u}^w(\mathbf{x}, s) ds \cdot \nabla \mathbf{u}^w \right\rangle.$$

The tracer equation is

$$\frac{\partial C_0}{\partial t_s} + \mathbf{V} \cdot \nabla C_0 = \kappa \nabla^2 C_0.$$

## Boundary Conditions

The surface boundary conditions at  $z = \eta(\mathbf{x}_h, t)$  are the following:

$$w = \frac{D\eta}{Dt}, \quad \tilde{p} = g\rho_0\eta + \tilde{p}_a, \quad \mathbf{v} \frac{\partial \mathbf{q}}{\partial z} = \frac{1}{\rho_0} \boldsymbol{\tau}, \quad \kappa \frac{\partial \tilde{C}}{\partial z} = \mathcal{I}.$$

Lead to (at  $z = 0$ )

$$w_0 = \nabla \cdot \mathbf{M}, \quad p_0 = \eta_0 + p_{a0} - P$$

$$\mathbf{v} \left( \frac{\partial \mathbf{v}_0}{\partial z} + \mathbf{S} \right) = \boldsymbol{\tau}, \quad \kappa \frac{\partial C_0}{\partial z} = \mathcal{I}.$$

where the *wave-induced adjustments* (at  $z = 0$ ) are

$$\mathbf{M} \equiv \left\langle \mathbf{u}^w \eta^w \right\rangle, \quad P \equiv \left\langle p_z^w \eta^w \right\rangle, \quad \mathbf{S} \equiv \left\langle \frac{\partial^2 \mathbf{u}^w}{\partial z^2} \eta^w \right\rangle.$$

# Currents, Shallow Water Wave Case

Momentum

$$\mathbf{v}_t + \mathbf{v} \cdot \nabla \mathbf{v} + f \hat{\mathbf{z}} \times \mathbf{v} + \nabla p = -\nabla K + \hat{\mathbf{z}} \times \mathbf{J}$$

Continuity

$$\eta_t + \nabla \cdot [H\mathbf{v}] = \nabla \cdot \mathbf{M}$$

Tracer Equation

$$C_t + \mathbf{v} \cdot \nabla C = \kappa \Delta C - \mathbf{u}^{St} \cdot \nabla C.$$

Boundary conditions are modified by the presence of waves and currents

# Waves, Shallow Water Wave Case

The sea elevation is represented by

$$\eta = \sum_j A_j(\mathbf{X}, \tau) e^{iS_j(\mathbf{X}, \tau)/\varepsilon^2} + c.c$$

where  $\mathbf{k}_j = -\nabla_{\mathbf{X}} S_j$ ,  $\omega_j = \partial_{\tau} S_j$ .

$$\begin{aligned} \mathbf{k}_t + \mathbf{C}_g \nabla_{\mathbf{X}} \mathbf{k} &= -\frac{k\sigma}{\sinh[2kH]} \nabla_{\mathbf{X}} H \\ \sigma_t + \mathbf{C}_g \cdot \nabla_{\mathbf{X}} \sigma &= 0 \end{aligned}$$

$\sigma^2 = k \tanh[kH]$  and the group velocity  $\mathbf{C}_g = \frac{\sigma}{2k^2} (1 + \frac{2kH}{\sinh[2kH]}) \mathbf{k}$ .

The amplitude of the waves obey

$$A_t + (\mathbf{C}_g + \mathbf{V}) \cdot \nabla_{\mathbf{X}} A + \frac{1}{2} A \nabla \cdot \mathbf{C}_g + \frac{i}{2} M |A|^2 A + i N A = 0$$

# Currents/Waves and Dissipation due to White Capping



$$d\mathbf{X}_t = \mathbf{V}(\mathbf{X}, t)dt + d\mathbf{W}_t(\mathbf{X}, t)$$

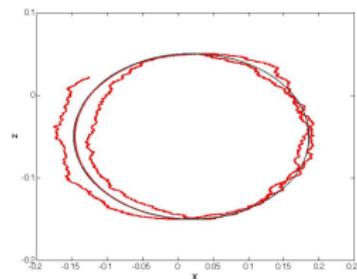
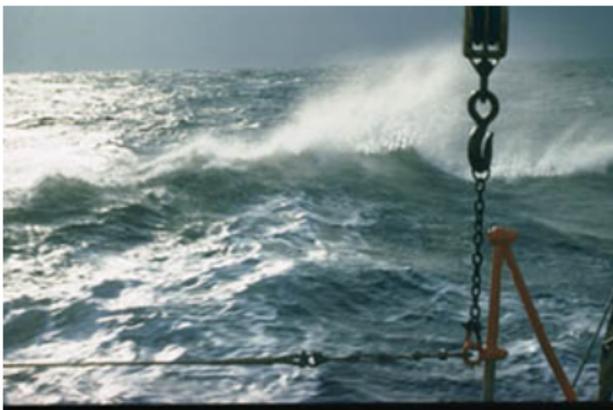


Figure: Stochastic

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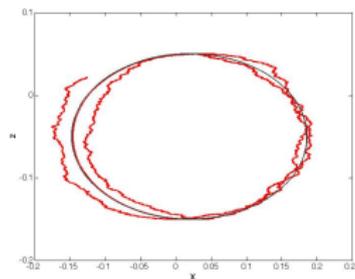


Figure: Stochastic

# Dissipative/Diffusion Current Model

The momentum with **dissipation** and **diffusion**:

$$\frac{\partial \mathbf{v}}{\partial T} = \mathbf{V} \times \mathbf{Z} - \nabla \Phi + \langle (\mathbf{B} \times \mathbf{Z}) + \mathbf{b} \times (\nabla \times \mathbf{b}) + [\mathbf{V} \times \nabla \times \mathbf{b}] - \frac{1}{2} \nabla |\mathbf{b}|^2 \rangle + \nabla \cdot \mathbf{R}$$

where  $\mathbf{V} = \mathbf{v} + \mathbf{u}^{stokes}$ ,  $\mathbf{Z} = \nabla \times \mathbf{v} + 2\Omega$  and  $\Phi = p_0 + \frac{1}{2} |\mathbf{V}|^2$ .

The **dissipation** contributes to the vortex force and the Bernoulli head.

The **diffusion** appears as a viscous term and accounts for boundary layer effects

The tracers obey

$$\frac{\partial C}{\partial T} + \mathbf{V} \cdot \nabla C = -\mathbf{B} \cdot \nabla C + \nabla \cdot \mathbf{Q}.$$

J. M. Restrepo *Wave Breaking Dissipation in the Wave-Driven Ocean Circulation* J. Phys. Oceanogr. (2007)

J.M. Restrepo, J. M. Ramírez, J.C. McWilliams & M. Banner *Wave Breaking Dissipation and Diffusion in Waves and Currents*, in preparation (2008)

Model  $\mathbf{b} := \mathbf{B} + \mathbf{b}'$  as the random sum

$$\mathbf{b}(\mathbf{x}_h, z, T) = \sum_{(\mathbf{X}_h, \tau) \in \Phi} \mathbf{b}_{E(\mathbf{X}_h, \tau)}(\mathbf{x}_h - \mathbf{X}_h, z) \delta(\tau - T)$$

where

$$\mathbf{b}_E(\mathbf{x}_h - \mathbf{X}_h, z) := \frac{1}{\tau_E} \int_0^{\tau_E} \tilde{\mathbf{b}}_E(\mathbf{x}_h - \mathbf{X}_h, z, t) dt$$

The ensemble average at  $(\mathbf{x}_h, z, T)$  of some functional  $\mathcal{F}$  of the field  $\mathbf{b}$  is:

$$\begin{aligned} \langle \mathcal{F}(\mathbf{b}) \rangle(\mathbf{x}_h, z, T) dT &:= \left\langle \sum_{(\mathbf{X}_h, \tau) \in \Phi} \mathcal{F}(\mathbf{b}_{E(\mathbf{X}_h, \tau)}(\mathbf{x}_h - \mathbf{X}_h, z)) \delta(T - \tau) \right\rangle \\ &= \int_{\mathbb{R}} \int_{\mathbf{x}_h - \Omega_E} \mathcal{F}(\mathbf{b}_E(\mathbf{x}_h - \mathbf{X}_h, z)) \Lambda(d\mathbf{X}_h, dT) p(E) dE. \end{aligned}$$

$$\mathbf{B}(z) = \int_{\mathbb{R}} \left[ \int_{\tilde{\Omega}_E} \mathbf{b}_E(\mathbf{X}_h, z, T) d\mathbf{X}_h dT \right] \lambda p(E) dE$$

# Diffusivity

The observation is that wave breaking increases the size of the mixing layer and this layer will then create a great deal of dissipation.

$$\mathbf{R}_v \approx \mathbf{v} \frac{\partial \mathbf{v}_h}{\partial z}, \quad \mathbf{R}_h \approx \mathbf{v} \nabla \mathbf{v}_h$$

$$\mathbf{Q}_v \approx \kappa \frac{\partial C}{\partial z}, \quad \mathbf{Q}_h \approx \kappa \nabla C.$$

We assume that

$$\mathbf{v} \sim \langle \ell_b |w^b| \rangle, \quad \kappa \sim \langle \ell_\theta |w^b| \rangle.$$

$w^b$  is the vertical component of the velocity associated with breaking, and the mixing length is

$$\ell_b = \gamma \eta(\mathbf{x}, t), \quad \ell_\theta = \alpha \eta(\mathbf{x}, t).$$

# Current Effects on Waves

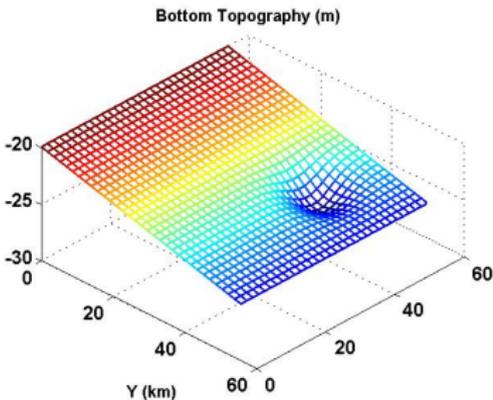


Figure: Bottom Topography

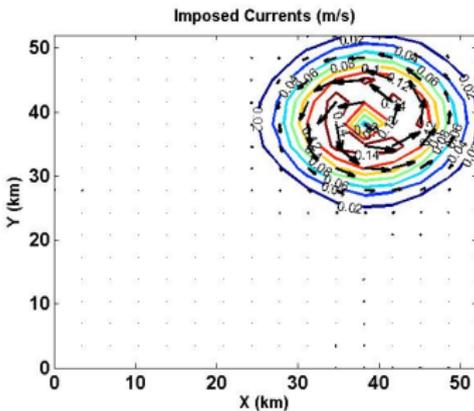


Figure: Current Forcing

# Current Effects on Waves

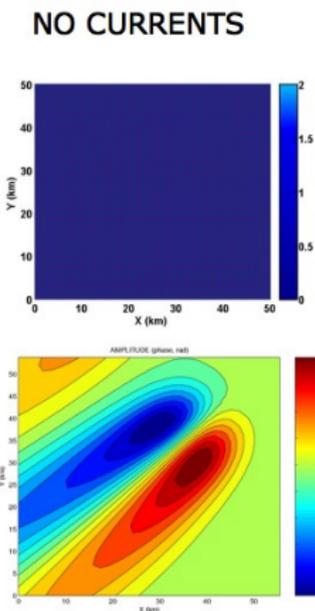


Figure: Waves, No Currents

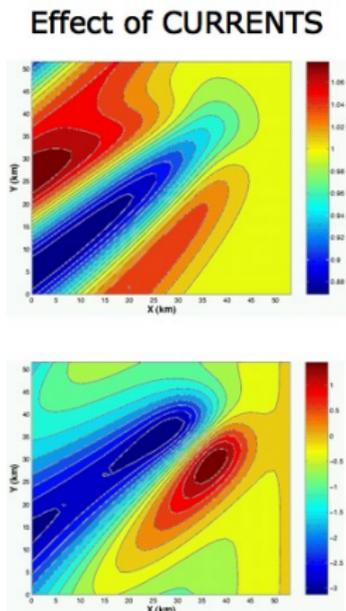
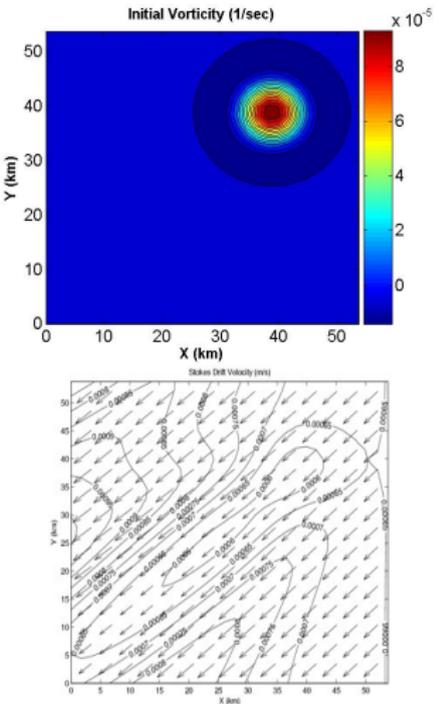
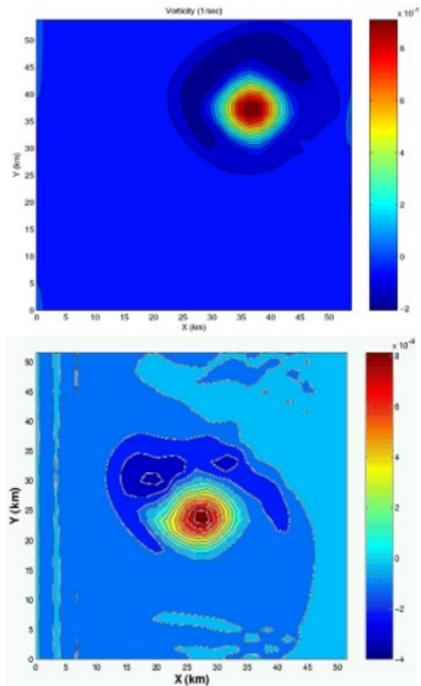


Figure: Waves, With Currents

# Wave Effects on Currents



**Figure:** Initial Current and Waves Forcing



**Figure:** No Waves, With Waves

# Diffusion and Wave Effects on Currents

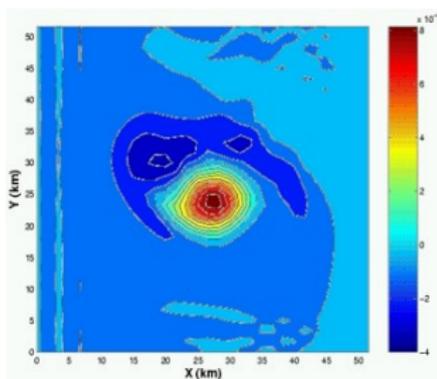


Figure: Without Diffusion

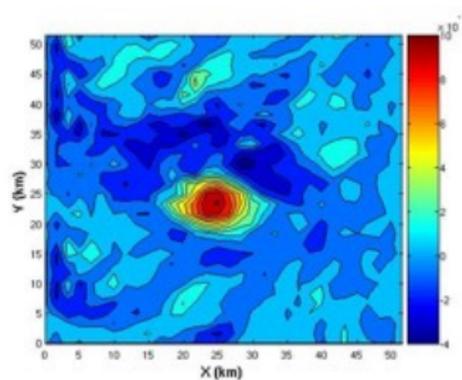


Figure: With Diffusion

# Wave Breaking Dissipation Model

How do you Determine Wave Dissipation (*i.e.*  $\mathbf{b}$ )?

- Determine the actual velocity  $\mathbf{b}$  from field data.
- Use a model.

# How do you *Model* Wave Dissipation (i.e. $\mathbf{b}$ )?

Solve

$$\partial_{\alpha} \mathbf{b} = \frac{1}{Re} \Delta_{\beta, \delta, \gamma} \mathbf{b} + \mathbf{a} \mathcal{X} \mathcal{Y} \mathcal{Z} \mathcal{T}$$

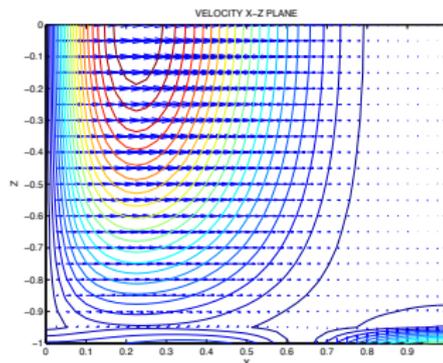
$$\nabla_{\beta, \delta, \gamma} \cdot \mathbf{b} = 0.$$

$$\mathcal{X} = \beta^3(1 - \beta^2), \quad 0 \leq \beta \leq 1,$$

$$\mathcal{Y} = 1 - (\delta - 1)^4, \quad 0 \leq \delta \leq 2,$$

$$\mathcal{Z} = (1 - (\gamma - 1)^4)^2, \quad 0 \leq \gamma \leq 2$$

$$\mathcal{T} = -(1 - \alpha^2)(1 - e^{5\alpha}), \quad 0 \leq$$



$(\alpha, \beta, \delta, \gamma)$  are scaled  $(t, x - ct, y, z - \chi ct)$ , where  $c$  is the wave speed,  $\chi c$  is the wave speed in the  $z$  direction.

# Coupling Wave Groups and Breaking Producing Dissipation

Waves expressed in terms of a carrier and an envelope:

$$\eta(\mathbf{X}_h, t) = \text{Re} \left\{ e^{i(\bar{\mathbf{k}}_h \cdot \mathbf{x}_h + \bar{\sigma}t)} \rho(\mathbf{x}_h, t) e^{i\theta(\mathbf{x}_h, t)} \right\}.$$

where

$$\mathbb{P}(\rho(\mathbf{x}_h, t) \in d\rho) = \frac{\rho}{2\pi\langle\eta^2\rangle} \exp \left\{ -\frac{\rho^2}{2\langle\eta^2\rangle} \right\}$$

a Rayleigh distribution.

The maximum wave group energy is defined as

$$\mu(t) = \max_{x \in \Omega(t)} \rho^2(x, t) k^2$$

The mean growth rate of wave group energy is

$$\delta(t) = \frac{1}{\bar{\sigma}} \frac{D\mu}{Dt}$$

# 2D Example

(Loading breakmovie)

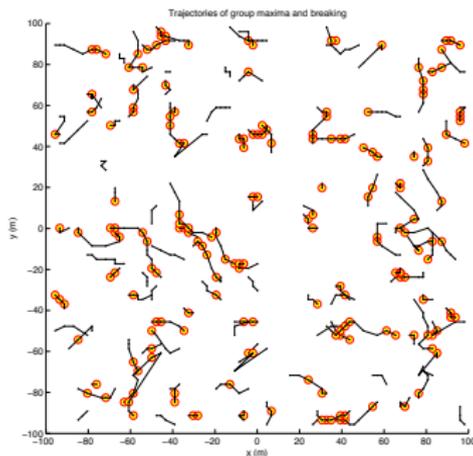


Figure: Dots indicate breaking events

Figure: Breaking Events  
Corresponding to the Movie.

# 2D Example

(Loading breakmovie)

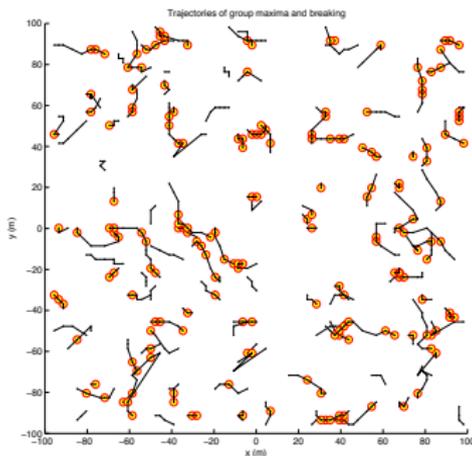


Figure: Dots indicate breaking events

Figure: Breaking Events  
Corresponding to the Movie.



# Progress Report

- We determined how wave breaking enters wave/current dynamics
  - Wave breaking dissipates waves.
  - Wave breaking affects currents via dissipation and diffusion.
  - Wave breaking affects the effect of residual flow due to waves.
- Proposed how to model breaking event.
  - Wave groups generate probability distribution of breaking events.
  - Can constrain breaking events via wind stress field.
  - Can make a more direct connection to field data (than conventional turbulence ideas).
- Could approach be extended to the problem of wind/wave interactions?

Further information:

Juan M. Restrepo

<http://www.physics.arizona.edu/~restrepo>